

Yang-Mills theory, lattice gauge theory and simulations

David Müller

Institute of Analysis
Johannes Kepler University Linz

dmueller@hep.itp.tuwien.ac.at

May 22, 2019

Overview

Introduction and physical context

Classical Yang-Mills theory

Lattice gauge theory

Simulating the Glasma in 2+1D

Introduction and physical context

Yang-Mills theory

- ▶ Formulated in 1954 by Chen Ning Yang and Robert Mills
- ▶ A non-Abelian gauge theory with gauge group $SU(N_c)$
- ▶ A non-linear generalization of electromagnetism, which is a gauge theory based on $U(1)$
- ▶ Gauge theories are a widely used concept in physics: the standard model of particle physics is based on a gauge theory with gauge group $U(1) \times SU(2) \times SU(3)$
- ▶ All fundamental forces (electromagnetism, weak and strong nuclear force, even gravity) are/can be formulated as gauge theories

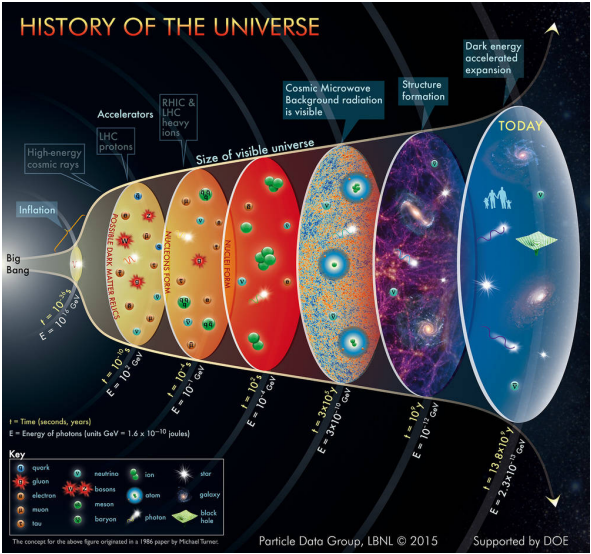
Classical Yang-Mills theory

Classical Yang-Mills theory refers to the study of the classical equations of motion (Euler-Lagrange equations) obtained from the Yang-Mills action

Main topic of this seminar: **solving the classical equations of motion of Yang-Mills theory numerically**

Not topic of this seminar: quantum field theory, path integrals, lattice quantum chromodynamics (except certain methods), the Millenium problem related to Yang-Mills ...

Classical Yang-Mills in the early universe



Classical Yang-Mills in the early universe

Electroweak phase transition: the electro-weak force splits into the weak nuclear force and the electromagnetic force

This phase transition can be studied using (extensions of) classical Yang-Mills theory

Literature:

- ▶ G. D. Moore and N. Turok, “Classical field dynamics of the electroweak phase transition”, PRD 55, 6538 (1997), [\[arXiv:hep-ph/9608350\]](#)
- ▶ Y. Akamatsu, A. Rothkopf and N. Yamamoto, “Non-Abelian chiral instabilities at high temperature on the lattice”, JHEP 1603, 210 (2016), [\[arXiv:1512.02374\]](#)
- ▶ ...

Classical Yang-Mills in heavy-ion collisions

My main application for Yang-Mills theory:

The earliest stages of relativistic heavy-ion collisions

Heavy-ion collisions

- ▶ Heavy-ion collision experiments (e.g. LHC at CERN or RHIC at BNL) to investigate the properties of nuclear matter under extreme conditions (high energy)
- ▶ Accelerate e.g. gold or lead nuclei to relativistic speeds, perform collisions, detect matter that is created (particle detectors)

Classical Yang-Mills in heavy-ion collisions

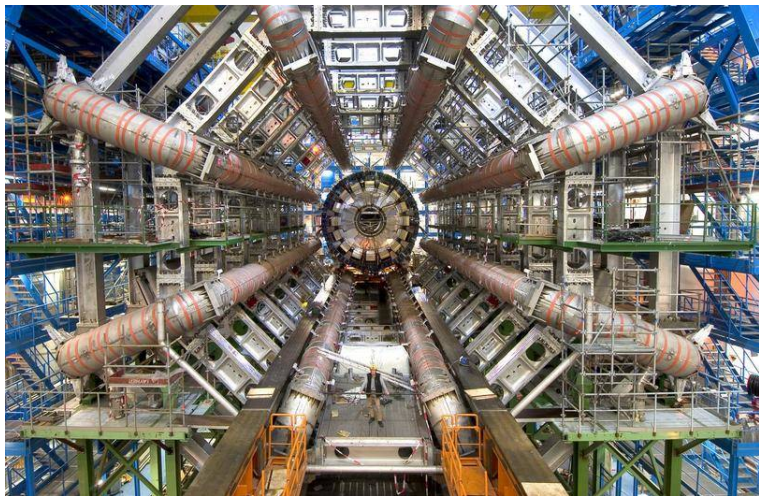


Image from ATLAS @ CERN (2005),

<https://home.cern/resources/image/experiments/atlas-images-gallery>

Classical Yang-Mills in heavy-ion collisions

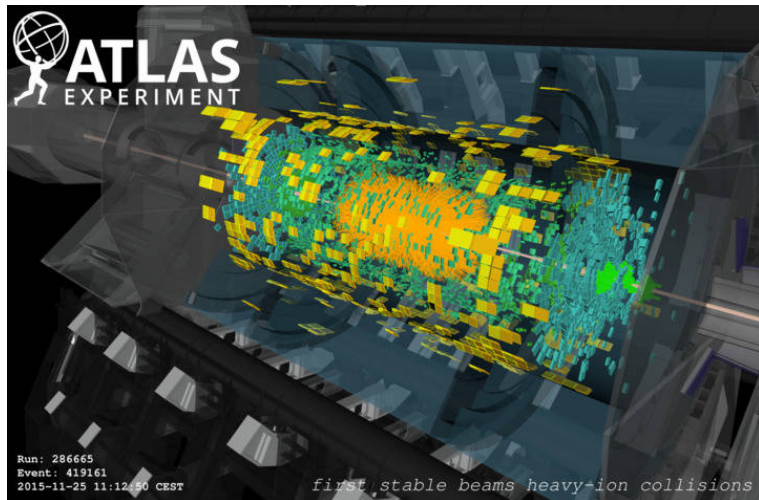


Image from ATLAS @ CERN (2015)

<https://atlas.cern/resources/multimedia/physics>

Classical Yang-Mills in heavy-ion collisions

- ▶ Heavy-ion collision experiments (e.g. LHC at CERN or RHIC at BNL) to investigate the properties of nuclear matter under extreme conditions (high energy)
- ▶ Fundamental theory: quantum chromodynamics (gauge group $SU(3)$) which governs the interactions of quarks and gluons
- ▶ At very high energies: nuclei appear as “frozen” thin disks, can be described using classical Yang-Mills theory (**color glass condensate**)
- ▶ Matter created immediately after the collision: “**Glasma**”
- ▶ Dynamics of the Glasma are described by classical Yang-Mills equations

Review:

- ▶ F. Gelis, “Color Glass Condensate and Glasma”, Int. J. Mod. Phys. A 28, 1330001 (2013) [[arXiv:1211.3327](https://arxiv.org/abs/1211.3327)]

Classical Yang-Mills in heavy-ion collisions

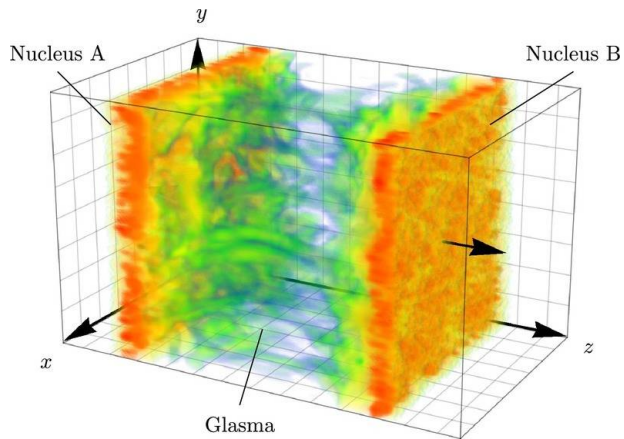


Image from my thesis [arXiv:1904.04267]

Lattice gauge theory and its application to heavy-ion collisions:

PhD thesis [[arXiv:1904.04267](https://arxiv.org/abs/1904.04267)] based on:

- ▶ D. Gelfand, A. Ipp, DM, “Simulating collisions of thick nuclei in the color glass condensate framework”, PRD94, 1, 014020 [[arXiv:1605.07184](https://arxiv.org/abs/1605.07184)]
- ▶ A. Ipp, DM, “Broken boost invariance in the Glasma via finite nuclei thickness”, PLB 771, 74 [[arXiv:1703.00017](https://arxiv.org/abs/1703.00017)]
- ▶ A. Ipp, DM, “Implicit schemes for real-time lattice gauge theory”, EPJC 78, no. 11, 884 [[arXiv:1804.01995](https://arxiv.org/abs/1804.01995)]

General (quantum) field theory, Yang-Mills theory:

- ▶ M. E. Peskin, D. V. Schroeder, “An Introduction To Quantum Field Theory” (1995)
- ▶ M. Srednicki, “Quantum Field Theory” (2007)
- ▶ D. Tong, “Lectures on Quantum Field Theory”, lecture notes <http://www.damtp.cam.ac.uk/user/tong/qft.html>

Lattice gauge theory:

- ▶ C. Gattringer, C. B. Lang, “Quantum Chromodynamics on the Lattice: An Introductory Presentation” (2009)

Classical Yang-Mills theory

Classical Yang-Mills theory: overview

- ▶ Preliminaries
 - ▶ Special relativity
 - ▶ Relativistic field theory
- ▶ Yang-Mills theory
 - ▶ Gauge fields and field strength tensor
 - ▶ Yang-Mills action
 - ▶ Variation of the action
- ▶ Gauge symmetry
 - ▶ Gauge fixing
 - ▶ Gauss constraint
- ▶ Energy-momentum tensor
- ▶ Electromagnetism

Preliminaries

Minkowski space

Minkowski space \mathbf{M} is a four-dimensional real vector space equipped with a metric $g_{\mu\nu}$ with signature $(+1, -1, -1, -1)$ (“mostly minus” convention, particle physics).

- ▶ Greek indices $\mu \in \{0, 1, 2, 3\}$ to indicate that a vector v^μ is an element of \mathbf{M} (a “4-vector”) or its tangent space
- ▶ Naming convention $v^\mu = (v^0, v^1, v^2, v^3)^T$
 - ▶ temporal component v^0
 - ▶ spatial components v^i , $i \in \{1, 2, 3\}$
- ▶ Latin indices for spatial components v^i
- ▶ Euclidean coordinate vector

$$x^\mu = (x^0, x^1, x^2, x^3)^T = (ct, x, y, z)^T$$

Speed of light c usually set to $c = 1$ (“natural” or particle physics units)

Minkowski metric

- ▶ Covariant metric in Euclidean coordinates

$$g_{\mu\nu} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

- ▶ **Einstein summation**: repeated indices are summed over
- ▶ Lowering indices

$$v_{\mu} \equiv g_{\mu\nu} v^{\nu} = (v^0, -v^i)^T$$

- ▶ Contravariant metric $g^{\mu\nu}$ is inverse of $g_{\mu\nu}$

$$g^{\mu\nu} g_{\nu\rho} = \delta_{\rho}^{\mu}$$

- ▶ Raising indices

$$v^{\mu} = g^{\mu\nu} v_{\nu}$$

Inner product and norm

Inner product of v^μ and w^μ

$$\begin{aligned}v \cdot w &\equiv v_\mu w^\mu \\ &= g_{\mu\nu} v^\mu w^\nu \\ &= v^T g w \\ &= v^0 w^0 - v^i w^i\end{aligned}$$

Norm of v^μ

$$v^2 \equiv v_\mu v^\mu = g_{\mu\nu} v^\mu v^\nu = (v^0)^2 - v^i v^i$$

Note: Minkowski norm is not positive-definite

Inner product and norm

Norm of v^μ using Minkowski metric $g_{\mu\nu}$

$$v^2 \equiv v_\mu v^\mu = g_{\mu\nu} v^\mu v^\nu = (v^0)^2 - v^i v^i$$

Nomenclature

- ▶ spacelike vector $v^2 < 0$
- ▶ timelike vector $v^2 > 0$
- ▶ lightlike vector $v^2 = 0$

Nomenclature depends on signature: different signs in general relativity, string theory

Lorentz group

The inner product of two 4-vectors $v_\mu w^\mu$ is invariant under transformations of the Lorentz group $O(1, 3)$.

$$v_\nu w^\nu = g_{\mu\nu} v^\mu w^\nu = v^0 w^0 - v^i w^i$$

1. $SO(3)$: rotations in \mathbb{R}^3 subspace
 2. Lorentz boosts (change of inertial frame)
 3. Time reversal $T : v^0 \rightarrow -v^0$
 4. Space inversion $P : v^i \rightarrow -v^i$
- ▶ $O(1, 3)$ consists of four connected components
 - ▶ $SO^+(1, 3)$: proper orthochronous Lorentz transformations, component connected to identity (leave out T and P)

Lorentz boosts

- ▶ Lorentz boosts correspond to a change of the inertial frame (“Bezugssystem”)
- ▶ Relativistic generalization of Galilean transformations
 $x' = x - v t$ with velocity v

Example: boost along $x^3 = z$ direction with “rapidity” $\eta \in \mathbb{R}$.

$$\begin{aligned}v'^{\mu} &= \Lambda^{\mu}_{\nu} v^{\nu} \\ &= (v^0 \cosh \eta + v^3 \sinh \eta, v^1, v^2, v^0 \sinh \eta + v^3 \cosh \eta)^T,\end{aligned}$$

where

$$\Lambda^{\mu}_{\nu} = \begin{pmatrix} \cosh \eta & 0 & 0 & -\sinh \eta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\sinh \eta & 0 & 0 & \cosh \eta \end{pmatrix}.$$

Lorentz boosts

Inner product is invariant under Lorentz boosts

$$v'^{\mu} = (v^0 \cosh \eta - v^3 \sinh \eta, v^1, v^2, v^0 \sinh \eta - v^3 \cosh \eta)^T,$$

$$w'^{\mu} = (w^0 \cosh \eta - w^3 \sinh \eta, w^1, w^2, w^0 \sinh \eta - w^3 \cosh \eta)^T,$$

$$\begin{aligned}v'_{\mu} w'^{\mu} &= g_{\mu\nu} v'^{\mu} w'^{\nu} \\&= v'^0 w'^0 - w'^i v'^i \\&= v^0 w^0 - w^i v^i \\&= v_{\mu} w^{\mu}.\end{aligned}$$

Lorentz boosts

- ▶ Velocity v_z from rapidity η

$$v = \tanh \eta$$
$$\cosh \eta = \frac{1}{\sqrt{1 - v_z^2}} = \gamma$$
$$\sinh \eta = \frac{v_z}{\sqrt{1 - v_z^2}} = v_z \gamma$$

- ▶ More familiar form of Lorentz boost

$$\Lambda_{\nu}^{\mu} = \begin{pmatrix} \gamma & 0 & 0 & -v_z \gamma \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\gamma v_z & 0 & 0 & \gamma \end{pmatrix}$$

- ▶ Lorentz factor $\gamma = 1/\sqrt{1 - v_z^2}$

Lorentz boosts

Apply boost to coordinate vector x^μ

$$\begin{aligned}x'^\mu &= \Lambda^\mu{}_\nu x^\nu, \\t' &= \gamma(t - v_z z), \\z' &= \gamma(z - v_z t).\end{aligned}$$

All standard results of special relativity follow from these transformations, e.g.

- ▶ Time dilation (fast moving clocks appear to run slower)
- ▶ Length contraction (fast moving objects appear length contracted)

Nuclei at relativistic speeds: “frozen”, thin disks of nuclear matter

Partial derivatives and integrals

Shorthand notation for partial derivatives with respect to coordinates

$$\partial_\mu \equiv \frac{\partial}{\partial x^\mu}$$

Partial derivative with raised index

$$\partial^\mu \equiv g^{\mu\nu} \partial_\nu = \frac{\partial}{\partial x_\mu}$$

Example: d'Alembert operator acting on function $\phi : \mathbf{M} \rightarrow \mathbb{R}$

$$\partial_\mu \partial^\mu \phi(x) = \frac{\partial^2 \phi(x)}{\partial t^2} - \Delta \phi(x)$$

with $x^0 = t$ as the time coordinate

Integrals over \mathbf{M} denoted as

$$\int_{\mathbf{x}} \phi(x) = \int d^4x \phi(x) = \int dt dx dy dz \phi(t, x, y, z)$$

Free scalar field

Action functional of a free scalar field $\phi(x) : \mathbf{M} \rightarrow \mathbb{R}$, which maps $\phi(x)$ to a real number

$$\begin{aligned} S[\phi] &= \int d^4x \left(\frac{1}{2} \partial_\mu \phi \partial^\mu \phi - \frac{1}{2} m^2 \phi^2 \right) \\ &= \int d^4x \mathcal{L}(\partial_\mu \phi(x), \phi(x), x) \end{aligned}$$

with mass parameter $m > 0$ and Lagrange density

$$\mathcal{L}(\partial_\mu \phi(x), \phi(x), x) = \frac{1}{2} \partial_\mu \phi \partial^\mu \phi - \frac{1}{2} m^2 \phi^2$$

Free scalar field

Action functional of a free scalar field

$$S[\phi] = \int d^4x \left(\frac{1}{2} \partial_\mu \phi \partial^\mu \phi - \frac{1}{2} m^2 \phi^2 \right)$$

- ▶ Invariant under Lorentz group (rotations, boosts, time reversal, space inversion) and translations

$$x'^{\mu} = x^{\mu} + w^{\mu}$$

(Lorentz group + translations: Poincaré group)

- ▶ Relativistic field theory:
consistent use of contracted 4-vector index pairs

Free scalar field

Principle of stationary action: a field ϕ which is an extremum of $S[\phi]$ satisfies the equations of motion (EOM) or Euler-Lagrange equations.

Directional functional derivative of $S[\phi]$ in “direction” $\alpha(x)$

$$\delta S[\phi, \alpha] \equiv \lim_{\epsilon \rightarrow 0} \frac{S[\phi + \epsilon\alpha] - S[\phi]}{\epsilon} = \int d^4x \frac{\delta S[\phi]}{\delta \phi(x)} \alpha(x)$$

Expression on the right requires integration by parts, $\alpha(x)$ has compact support on \mathbf{M}

Principle of stationary action

Different way of writing the same thing:

Variation of the action

$$\delta S[\phi, \delta\phi] = \int d^4x \frac{\delta S[\phi]}{\delta\phi(x)} \delta\phi(x)$$

Compare to total differential of $F(x_1, x_2, \dots, x_n) : \mathbb{R}^n \rightarrow \mathbb{R}$

$$dF = \sum_{i=1}^n \frac{\partial F}{\partial x_i} dx_i$$

Equations of motion (Euler-Lagrange eqs.) follow from

$$\delta S[\phi, \delta\phi] = 0 \quad \Leftrightarrow \quad \frac{\delta S[\phi]}{\delta\phi(x)} = 0$$

Free scalar field

Action of a free scalar field

$$S[\phi] = \int d^4x \left(\frac{1}{2} \partial_\mu \phi \partial^\mu \phi - \frac{1}{2} m^2 \phi^2 \right)$$

Variation of the action

$$\begin{aligned} \delta S[\phi, \delta\phi] &= \int d^4x \left(\partial_\mu \phi(x) \partial^\mu \delta\phi(x) - m^2 \phi(x) \delta\phi(x) \right) \\ &= \int d^4x \left(-\partial_\mu \partial^\mu \phi(x) - m^2 \phi(x) \right) \delta\phi(x) \end{aligned}$$

Note: integration by parts, no boundary terms

Functional derivative

$$\frac{\delta S[\phi]}{\delta \phi(x)} = -\partial_\mu \partial^\mu \phi(x) - m^2 \phi(x)$$

Free scalar field

Action of a free scalar field

$$S[\phi] = \int d^4x \left(\frac{1}{2} \partial_\mu \phi \partial^\mu \phi - \frac{1}{2} m^2 \phi^2 \right)$$

Principle of stationary action

$$\frac{\delta S[\phi]}{\delta \phi(x)} = -\partial_\mu \partial^\mu \phi(x) - m^2 \phi(x) = 0$$

Klein-Gordon equation (second order in time derivatives)

$$\frac{\partial^2 \phi(x)}{\partial t^2} - \Delta \phi(x) + m^2 \phi(x) = 0$$

Free scalar field

Lagrangian density for free scalar field

$$\mathcal{L}(\partial_\mu\phi(x), \phi(x), x) = \frac{1}{2}\partial_\mu\phi\partial^\mu\phi - \frac{1}{2}m^2\phi^2$$

Introduce conjugate momentum to $\phi(x)$

$$\pi(x) \equiv \frac{\partial\mathcal{L}}{\partial(\partial^0\phi)} = \partial_0\phi(x)$$

Rewrite Klein-Gordon equation(s) (first order in time derivatives)

$$\partial_0\pi(x) = \Delta\phi(x) - m^2\phi(x)$$

$$\partial_0\phi(x) = \pi(x)$$

Initial value problem: specify initial values $\phi(t_0, \vec{x})$ and $\pi(t_0, \vec{x})$ at some time t_0 and solve the equations of motion

Yang-Mills theory

Yang-Mills gauge fields

Degrees of freedom (DOF) in Yang-Mills theory are

gauge fields $A_\mu(x) : \mathbf{M} \rightarrow \mathfrak{su}(N_c)$

- ▶ Number of colors N_c
Quantum chromodynamics $N_c = 3$ (strong nuclear force)
Weak nuclear force $N_c = 2$
- ▶ Lie algebra $\mathfrak{su}(N_c)$
Traceless hermitian matrices in $\mathbb{C}^{N_c \times N_c}$

$$t \in \mathbb{C}^{N_c \times N_c}, \quad t = t^\dagger, \quad \text{tr}[t] = 0$$

For $t, t' \in \mathfrak{su}(N_c)$ we have

Scalar multiplication: $\alpha t \in \mathfrak{su}(N_c), \quad \alpha \in \mathbb{R}$

Addition: $t + t' \in \mathfrak{su}(N_c),$

Commutator: $[t, t'] / i \in \mathfrak{su}(N_c), \quad i^2 = -1$

Yang-Mills gauge fields

Degrees of freedom (DOF) in Yang-Mills theory are
gauge fields $A_\mu(x) : \mathbf{M} \rightarrow \mathfrak{su}(N_c)$

$$A_\mu(x) = A_\mu^a(x)t^a$$

- ▶ Color indices $a \in \{1, 2, \dots, N_c^2 - 1\}$ (Einstein summation)
- ▶ Color components $A_\mu^a(x)$ of gauge field
($4(N_c^2 - 1)$ functions $\mathbf{M} \rightarrow \mathbb{R}$)

Generators $t^a \in \mathfrak{su}(N_c)$

- ▶ $N_c = 2$: Pauli matrices $t^a = \frac{1}{2}\sigma^a$
- ▶ $N_c = 3$: Gell-Mann matrices $t^a = \frac{1}{2}\lambda^a$

Gauge fields are traceless and hermitian

Pauli-Matrices

$$\sigma_1 = \sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\sigma_2 = \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$\sigma_3 = \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Generators of $\mathfrak{su}(2)$:

$$t^a = \frac{1}{2}\sigma^a$$

Gell-Mann matrices

$$\lambda_1 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \lambda_2 = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \lambda_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\lambda_4 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \quad \lambda_5 = \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix}$$

$$\lambda_6 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \quad \lambda_7 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \quad \lambda_8 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$

Generators of $\mathfrak{su}(3)$:

$$t^a = \frac{1}{2} \lambda^a$$

Properties of generators

- ▶ Traceless

$$\text{tr}[t^a] = 0$$

- ▶ Hermitian

$$t^{a\dagger} = t^a$$

- ▶ Normalization

$$\text{tr}[t^a t^b] = \frac{1}{2} \delta^{ab}$$

- ▶ Antisymmetric structure constants f^{abc} (commutator)

$$[t^a, t^b] = t^a t^b - t^b t^a = if^{abc} t^c, \quad f^{abc} \in \mathbb{R}$$

- ▶ Symmetric structure constants d^{abc} (anti-commutator)

$$\{t^a, t^b\} = t^a t^b + t^b t^a = \frac{1}{N_c} \delta^{ab} \mathbf{1} + d^{abc} t^c, \quad d^{abc} \in \mathbb{R}$$

Yang-Mills field strength tensor

Definition: field strength tensor

$$F_{\mu\nu}(x) \equiv \partial_\mu A_\nu(x) - \partial_\nu A_\mu(x) + ig [A_\mu(x), A_\nu(x)]$$

with Yang-Mills coupling constant $g > 0$

$F_{\mu\nu}$ is antisymmetric in index pair μ, ν

$F_{\mu\nu}$ is traceless and hermitian

$$F_{\mu\nu}(x) = F_{\mu\nu}^a(x) t^a$$

Using $[t^a, t^b] = if^{abc} t^c$ we can write

$$F_{\mu\nu}^a(x) = \partial_\mu A_\nu^a(x) - \partial_\nu A_\mu^a(x) - gf^{abc} A_\mu^b(x) A_\nu^c(x)$$

Yang-Mills field strength tensor

Physical interpretation: field strength tensor contains the chromo-electric and -magnetic fields

$$F_{\mu\nu} = \begin{pmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & -B_z & B_y \\ -E_y & B_z & 0 & -B_x \\ -E_z & -B_y & B_x & 0 \end{pmatrix}$$

Electric fields

$$F_{0i} = E_i \in \mathfrak{su}(N_c).$$

Magnetic fields

$$F_{ij} = \varepsilon_{ijk} B_k, \quad B_i = -\frac{1}{2} \varepsilon_{ijk} F_{jk} \in \mathfrak{su}(N_c),$$

where ε_{ijk} is the Levi-Civita symbol

$$\varepsilon_{123} = 1, \quad \varepsilon_{ijk} = -\varepsilon_{jik} = -\varepsilon_{ikj}.$$

Yang-Mills action

Using $F_{\mu\nu}$ we can define the **Yang-Mills action** $S[A_\mu]$

$$\begin{aligned} S[A_\mu] &= \int d^4x \operatorname{tr} \left(-\frac{1}{2} F_{\mu\nu}(x) F^{\mu\nu}(x) \right) \\ &= \int d^4x \operatorname{tr} \left(-\frac{1}{2} g^{\mu\rho} g^{\nu\sigma} F_{\mu\nu}(x) F_{\rho\sigma}(x) \right) \end{aligned}$$

Consistent use of contracted index pairs: invariant under Lorentz transformations (rotations, boosts, time reversal, spatial inversion) and translations

\Rightarrow Varying this action yields the Yang-Mills equations for $A_\mu(x)$

Varying the Yang-Mills action

Using integration by parts, properties of the commutator and the trace, we find

$$\begin{aligned}\delta S[A_\mu, \delta A_\mu] &= \int d^4x \operatorname{tr}[-F^{\mu\nu} \delta F_{\mu\nu}] \\ &= \int d^4x \operatorname{tr}[-F^{\mu\nu} (\partial_\mu \delta A_\nu - \partial_\nu \delta A_\mu \\ &\quad + ig [\delta A_\mu, A_\nu] + ig [A_\mu, \delta A_\nu])] \\ &= -2 \int d^4x \operatorname{tr}[(\partial_\nu F^{\mu\nu} + ig [A_\nu, F^{\mu\nu}]) \delta A_\mu]\end{aligned}$$

Vanishing variation $\delta S[A_\mu, \delta A_\mu] = 0$:

Yang-Mills equations

$$\partial_\nu F^{\mu\nu} + ig [A_\nu, F^{\mu\nu}] = 0$$

Yang-Mills equations

Yang-Mills equations

$$\partial_\nu F^{\mu\nu} + ig [A_\nu, F^{\mu\nu}] = 0$$

with field strength

$$F_{\mu\nu} \equiv \partial_\mu A_\nu - \partial_\nu A_\mu + ig [A_\mu, A_\nu]$$

Shorthand: (gauge) covariant derivative D_μ

For an algebra-valued field $B(x)$ we define

$$D_\mu B(x) \equiv \partial_\mu B(x) + ig [A_\mu(x), B(x)]$$

Write Yang-Mills equations as

$$D_\nu F^{\mu\nu} = 0$$

Yang-Mills equations

Yang-Mills equations in terms of color components A_μ^a

$$A_\mu = A_\mu^a t^a$$

$$\begin{aligned} & \partial_\nu \partial^\mu A^{a,\nu} - \partial_\nu \partial^\nu A^{a,\mu} \\ & - g f^{abc} \left(\partial_\nu A^{b,\mu} A^{c,\nu} + A^{b,\mu} \partial_\nu A^{c,\nu} \right) - g f^{abc} A_\nu^b \left(\partial^\mu A^{c,\nu} - \partial^\nu A^{c,\mu} \right) \\ & + g^2 f^{abc} f^{cde} A_\nu^b A^{d,\mu} A^{e,\nu} = 0 \end{aligned}$$

For $N_c = 3$: system of 32 coupled, second order hyperbolic, non-linear PDEs

Yang-Mills equations

Reformulate the second order system into a first order system
Introduce conjugate momenta

$$\pi^{a,\mu} = \frac{\partial \mathcal{L}}{\partial (\partial_0 A_\mu^a)} = -F^{a,0\mu}$$

$$\pi^0 = 0, \quad \pi^i = F_{0i} = E_i$$

The momentum π^0 conjugate to A_0 vanishes.

Degrees of freedom

- ▶ A_0^a, A_i^a : $4(N_c^2 - 1)$ gauge fields
- ▶ π^i : $3(N_c^2 - 1)$ momenta

Yang-Mills equations

Rewrite Yang-Mills equations using canonical momenta π^i
Equations of motion

$$\partial_\mu F^{\mu i} + ig [A_\mu, F^{\mu i}] = 0$$
$$\pi^i = F_{0i} = \partial_0 A_i - \partial_i A_0 + ig [A_0, A_i]$$

$$\Rightarrow \partial_0 \pi^i = -ig [A_0, \pi^i] + \partial_j F^{ji} + ig [A_j, F^{ji}]$$
$$\Rightarrow \partial_0 A_i = \pi^i + \partial_i A_0 - ig [A_0, A_i]$$

Gauss constraint (contains no time derivatives of π^i or A_μ)

$$\partial_\mu F^{\mu 0} + ig [A_\mu, F^{\mu 0}] = 0$$
$$\Rightarrow \partial_i \pi^i + ig [A_i, \pi^i] = 0$$

Yang-Mills equations

Reformulated system

$$\partial_0 \pi^i = -ig [A_0, \pi^i] + \partial_j F^{ji} + ig [A_j, F^{ji}]$$

$$\partial_0 A_i = \pi^i + \partial_i A_0 - ig [A_0, A_i]$$

$$\partial_i \pi^i + ig [A_i, \pi^i] = 0$$

There is no term $\partial_0 A_0$. This system is not solvable as a standard initial value problem. Specifying $A_0(t_0, \vec{x})$, $A_i(t_0, \vec{x})$ and $\pi^i(t_0, \vec{x})$ at some initial time t_0 is **not enough information** to determine the fields at some later time $t_1 > t_0$.

The Yang-Mills equations (as stated above) are under-determined:
gauge symmetry

Yang-Mills in 1+1D, single color component

Reduce dimensions to 1 + 1 (t and x) $\Rightarrow A_0(t, x)$ and $A_1(t, x)$

Yang-Mills equations:

$$\partial_0 \pi^1 = -ig [A_0, \pi^1]$$

$$\partial_0 A_1 = \pi^1 + \partial_1 A_0 - ig [A_0, A_1]$$

$$\partial_1 \pi^1 + ig [A_1, \pi^1] = 0$$

Reduce to a single color component:

$A_0 = A_0^1 t^1$, $A_1 = A_1^1 t^1 \Rightarrow$ drop all commutator terms

Yang-Mills in 1+1D, single color component

Remove commutator terms:

$$\partial_0 \pi^1 = 0$$

$$\partial_0 A_1 = \pi^1 + \partial_1 A_0$$

$$\partial_1 \pi^1 = 0$$

From first and third equation: π^1 must be constant w.r.t t and x

$$\pi^1 = C$$

Solution of second equation with initial data at t_0 :

$$A_1(t, x) = A_1(t_0, x) + (t - t_0)C + \int_{t_0}^t dt' \partial_1 A_0(t', x)$$

Cannot compute $A_1(t, x)$ without specifying $A_0(t, x)$.

Gauge symmetry

Gauge symmetry

Special unitary group $SU(N_c)$

Special unitary matrices acting on \mathbb{C}^{N_c}

$$U \in \mathbb{C}^{N_c \times N_c}, \quad UU^\dagger = U^\dagger U = \mathbf{1}, \quad \det U = 1$$

For $U, U', U'' \in SU(N_c)$ we have

$$\text{Multiplication:} \quad UU' \in SU(N_c)$$

$$\text{Associativity:} \quad (UU')U'' = U(U'U'')$$

$$\text{Identity:} \quad \mathbf{1}U = U\mathbf{1}$$

$$\text{Inverse:} \quad U^\dagger U = \mathbf{1}$$

$SU(N_c)$ is a finite-dimensional real smooth manifold. Inverse and multiplication are smooth maps. $SU(N_c)$ is a Lie group.

Gauge symmetry

Connection between Lie algebra $\mathfrak{su}(N_c)$ and Lie group $SU(N_c)$:
the exponential map $\exp : \mathfrak{su}(N_c) \rightarrow SU(N_c)$

Elements of the Lie algebra “generate” elements of the Lie group
via

$$U = \exp(it), \quad t \in \mathfrak{su}(N_c), \quad i^2 = -1$$

Definition as a series:

$$U = \exp(it) = \sum_{n=0}^{\infty} \frac{1}{n!} (it)^n$$

Some useful properties:

$$\exp(it) \exp(it') = \exp(i(t + t')), \quad [t, t'] = 0, \quad t, t' \in \mathfrak{su}(N_c)$$

$$(\exp(it))^{-1} = \exp(-it), \quad t \in \mathfrak{su}(N_c)$$

Gauge symmetry

The Yang-Mills action for N_c colors exhibits a particular local symmetry: $SU(N_c)$ gauge symmetry

Consider a “local gauge transformation”, a smooth function $\Omega(x) : \mathbf{M} \rightarrow SU(N_c)$ acting on a gauge field $A_\mu(x)$

$$\begin{aligned} A'_\mu(x) &= \Omega(x) \left(A_\mu(x) + \frac{1}{ig} \partial_\mu \right) \Omega^\dagger(x) \\ &= \Omega(x) A_\mu(x) \Omega^\dagger(x) + \frac{1}{ig} \Omega(x) \partial_\mu \Omega^\dagger(x) \end{aligned}$$

\Rightarrow Gauge transformation of the field strength tensor

$$F'_{\mu\nu}(x) = \Omega(x) F_{\mu\nu}(x) \Omega^\dagger(x)$$

How does $S[A_\mu]$ change under this transformation?

Gauge symmetry

Gauge transformation of the field strength tensor

$$F'_{\mu\nu}(x) = \Omega(x)F_{\mu\nu}(x)\Omega^\dagger(x)$$

Transformation of $S[A_\mu]$

$$\begin{aligned} S[A'_\mu] &= \int d^4x \operatorname{tr} \left(-\frac{1}{2} F'_{\mu\nu}(x) F'^{\mu\nu}(x) \right) \\ &= \int d^4x \operatorname{tr} \left(-\frac{1}{2} \Omega(x) F_{\mu\nu}(x) \Omega^\dagger(x) \Omega(x) F^{\mu\nu}(x) \Omega^\dagger(x) \right) \\ &= S[A_\mu] \end{aligned}$$

The Yang-Mills action is **invariant** under local gauge transformations $\Omega(x)$.

Gauge symmetry: implications

- ▶ If A_μ solves the Yang-Mills (YM) equations, then A'_μ does too
- ▶ Gauge symmetry reflects the degree of redundancy in the gauge field description of gauge field theories
- ▶ Physical observables must be **gauge invariant**
 - ▶ Gauge field A_μ is not an observable

$$A'_\mu = \Omega \left(A_\mu + \frac{1}{ig} \partial_\mu \right) \Omega^\dagger$$

- ▶ Field strength tensor $F_{\mu\nu}$ is not an observable

$$F'_{\mu\nu} = \Omega F_{\mu\nu} \Omega^\dagger$$

- ▶ Physical observables like the energy-momentum tensor $T_{\mu\nu}$ are gauge invariant

$$T'_{\mu\nu} = T_{\mu\nu}$$

Gauge symmetry

Proof: if A_μ solves the YM equations, then A'_μ does too.

1) Assume that A_μ solves the YM equations

$$\partial_\nu F^{\mu\nu} + ig [A_\nu, F^{\mu\nu}] = 0$$

2) Check if A'_μ solves them too:

$$A'_\mu = \Omega \left(A_\mu + \frac{1}{ig} \partial_\mu \right) \Omega^\dagger, \quad F'_{\mu\nu} = \Omega F_{\mu\nu} \Omega^\dagger$$

$$\partial_\nu F'^{\mu\nu} = \Omega \left(\partial_\nu F^{\mu\nu} - \left[\partial_\nu \Omega^\dagger \Omega, F^{\mu\nu} \right] \right) \Omega^\dagger$$

$$ig [A'_\nu, F'^{\mu\nu}] = \Omega \left(ig [A_\nu, F^{\mu\nu}] + \left[\partial_\nu \Omega^\dagger \Omega, F^{\mu\nu} \right] \right) \Omega^\dagger$$

$$\Rightarrow \partial_\nu F'^{\mu\nu} + ig [A'_\nu, F'^{\mu\nu}] = \Omega (\partial_\nu F^{\mu\nu} + ig [A_\nu, F^{\mu\nu}]) \Omega^\dagger = 0$$

Gauge symmetry

Proof: if A_μ solves the YM equations, then A'_μ does too.

Short version: if A_μ is an extremum of the action ($\delta S = 0$), then A'_μ also satisfies $\delta S = 0$ due to gauge symmetry $S[A_\mu] = S[A'_\mu]$.

$$A'_\mu + \delta A'_\mu = \Omega \left(A_\mu + \delta A_\mu + \frac{1}{ig} \partial_\mu \right) \Omega^\dagger$$
$$\Rightarrow \delta A'_\mu = \Omega \delta A_\mu \Omega^\dagger$$

Variation is invariant:

$$\begin{aligned} \delta S[A'_\mu, \delta A'_\mu] &= -2 \int d^4x \operatorname{tr} \left[(\partial_\nu F'^{\mu\nu} + ig [A'_\nu, F'^{\mu\nu}]) \delta A'_\mu \right] \\ &= -2 \int d^4x \operatorname{tr} \left[\Omega (\partial_\nu F^{\mu\nu} + ig [A_\nu, F^{\mu\nu}]) \Omega^\dagger \Omega \delta A_\mu \Omega^\dagger \right] \\ &= \delta S[A_\mu, \delta A_\mu] = 0. \end{aligned}$$

Gauge fixing

A_μ and A'_μ are said to be gauge equivalent (belong to the same equivalence class) if there exists a gauge transformation Ω which satisfies

$$A'_\mu = \Omega(A_\mu + \frac{1}{ig}\partial_\mu)\Omega^\dagger$$

Equivalence classes are also known as “gauge orbits”.

Lots of freedom to choose how a particular solution to the YM equations looks. Is there a solution within an equivalence class that is particularly simple? Is there a way to make the YM equations easier to solve by restricting the “gauge freedom”?

Idea: reduce the gauge freedom by “fixing” the gauge symmetry. Supplement YM equations with a **gauge fixing condition** $G[A_\mu] = 0$.

Gauge fixing

Supplement YM equations with a **gauge fixing condition**

$$G[A_\mu] = 0$$

What can $G[A_\mu]$ be? Gauge fixing condition must be **realizable**:

Suppose A_μ does not satisfy the gauge condition $G[A_\mu] \neq 0$. If G is realizable, then there must exist a gauge transformation Ω such that $A'_\mu = \Omega(A_\mu + \frac{1}{ig}\partial_\mu)\Omega^\dagger$ satisfies $G[A'_\mu] = 0$.

Gauge fixing

Some popular, commonly used gauge fixing conditions:

- ▶ Temporal (axial) gauge

$$A^0(x) = A_0(x) = 0, \quad \forall x \in \mathbf{M}$$

Similar: spatial axial gauges $A_i(x) = 0$

- ▶ Coulomb gauge

$$\partial_i A^i(x) = 0, \quad \forall x \in \mathbf{M}$$

Note: sum only over spatial indices $i \in \{1, 2, 3\}$

- ▶ Covariant (Lorenz) gauge

$$\partial_\mu A^\mu(x) = 0, \quad \forall x \in \mathbf{M}$$

Note: use of contracted 4-vector indices, invariant under Lorentz group

Temporal gauge

Temporal gauge $A_0(x) = 0$ is very useful for numerical simulations

Is temporal gauge realizable?

Consider A_μ with $A_0 \neq 0$. Can we find a gauge transformation Ω such that

$$A'_0 = \Omega \left(A_0 + \frac{1}{ig} \partial_0 \right) \Omega^\dagger = 0$$

$\Rightarrow \Omega^\dagger(t, \vec{x})$ must satisfy

$$\partial_0 \Omega^\dagger(t, \vec{x}) = -ig A_0(t, \vec{x}) \Omega^\dagger(t, \vec{x})$$

where $x^0 = t$ and $\vec{x} = (x^1, x^2, x^3)^T$

Temporal gauge

The equation

$$\partial_t \Omega^\dagger(t, \vec{x}) = -igA_0(t, \vec{x})\Omega^\dagger(t, \vec{x})$$

is solved by the path-ordered exponential

$$\Omega^\dagger(t, \vec{x}) = \mathcal{P} \exp \left(-ig \int_{-\infty}^t dt' A_0(t', \vec{x}) \right)$$

with $\lim_{t \rightarrow -\infty} \Omega(t, \vec{x}) = \mathbf{1}$ and \mathcal{P} denotes **path ordering**.

Path-ordering

Consider a smooth path $x(s) : \mathbb{R} \rightarrow \mathbf{M}$ parameterized by $s \in [0, 1]$ and the gauge field along the path $A(s) = \frac{dx^\mu(s)}{ds} A_\mu(x(s))$. The path ordering symbol \mathcal{P} orders products according to the parameter s

$$\mathcal{P} [A(s)A(s')] = \begin{cases} A(s)A(s'), & \text{for } s \geq s' \\ A(s')A(s), & \text{for } s < s' \end{cases}$$

Convention: “left means later”

Alternative expression using the Heaviside step function θ

$$\mathcal{P} [A(s)A(s')] = \theta(s - s')A(s)A(s') + \theta(s' - s)A(s')A(s)$$

Path-ordered exponential

Definition as series

For $t_A < t_B$:

$$\begin{aligned}\mathcal{P} \exp \left(-ig \int_{t_A}^{t_B} dt' A_0(t', \vec{x}) \right) &= \mathbf{1} + \sum_{n=1}^{\infty} \frac{1}{n!} \mathcal{P} \left[-ig \int_{t_A}^{t_B} dt' A_0(t') \right]^n \\ &= \mathbf{1} + \sum_{n=1}^{\infty} \frac{1}{n!} (-ig)^n \int_{t_A}^{t_B} dt'_1 \int_{t_A}^{t'_1} dt'_2 \cdots \int_{t_A}^{t'_{n-1}} dt'_n \mathcal{P} [A_0(t'_1) A_0(t'_2) \cdots A_0(t'_n)] \\ &= \mathbf{1} + \sum_{n=1}^{\infty} (-ig)^n \int_{t_A}^{t_B} dt'_1 \int_{t_A}^{t'_1} dt'_2 \cdots \int_{t_A}^{t'_{n-1}} dt'_n A_0(t'_1) A_0(t'_2) \cdots A_0(t'_n)\end{aligned}$$

Path-ordered exponential

Definition using products

Discretize interval $t \in [t_A, t_B]$ as set: $t \in \{t_0, t_1, \dots, t_n\}$ with $t_0 = t_A$, $t_n = t_B$ and $\Delta t = (t_B - t_A)/n$.

$$\begin{aligned} \mathcal{P} \exp \left(-ig \int_{t_A}^{t_B} dt' A_0(t', \vec{x}) \right) &= \lim_{n \rightarrow \infty} \mathcal{P} \prod_{i=0}^{n-1} (\mathbf{1} - ig \Delta t A_0(t_i)) \\ &= \lim_{n \rightarrow \infty} (\mathbf{1} - ig \Delta t A_0(t_n)) (\mathbf{1} - ig \Delta t A_0(t_{n-1})) \cdots (\mathbf{1} - ig \Delta t A_0(t_0)) \end{aligned}$$

Path-ordered exponential

Derivative of path ordered exponential

What is $\partial_t \Omega^\dagger(t)$?

$$\partial_t \Omega^\dagger(t, \vec{x}) = \lim_{\epsilon \rightarrow 0} \frac{\Omega^\dagger(t + \epsilon) - \Omega^\dagger(t)}{\epsilon}$$

From product definition of the path ordered exponential we know

$$\Omega^\dagger(t + \epsilon) \approx (\mathbf{1} - ig\epsilon A_0(t)) \Omega^\dagger(t) + \mathcal{O}(\epsilon^2)$$

Inserting this into the differential quotient yields

$$\partial_t \Omega^\dagger(t) = -igA_0(t)\Omega^\dagger(t)$$

Temporal gauge: summary

Temporal gauge is defined as the condition

$$A_0 = 0$$

Temporal gauge is realizable: for any $A_0 \neq 0$ we can find a gauge transformation such that $A'_0 = 0$.

The gauge transformed fields are given by

$$A'_i = \Omega(A_i + \frac{1}{ig}\partial_i)\Omega^\dagger, \quad A'_0 = 0$$

with the path-ordered exponential

$$\Omega^\dagger(t, \vec{x}) = \mathcal{P} \exp \left(-ig \int_{-\infty}^t dt' A_0(t', \vec{x}) \right)$$

Yang-Mills equations in temporal gauge

Back to the Yang-Mills equations ...

Recall conjugate momentum π^i

$$\begin{aligned}\pi^i &= \frac{\partial \mathcal{L}}{\partial (\partial_0 A_i)} \\ &= F_{0i} \\ &= \partial_0 A_i - \partial_i A_0 + ig [A_0, A_i] \\ &= \partial_0 A_i\end{aligned}$$

Much simpler expression in temporal gauge.

Yang-Mills equations in temporal gauge

By eliminating A_0 , the Yang-Mills equations can be solved as an initial value problem.

$$\partial_0 \pi^i = \partial_j F^{ji} + ig [A_j, F^{ji}]$$

$$\partial_0 A_i = \pi^i$$

$$\partial_i \pi^i + ig [A_i, \pi^i] = 0$$

It is sufficient to specify $A_i(t_0, \vec{x})$, $\pi^i(t_0, \vec{x})$ (assuming they satisfy the Gauss constraint) to find A_i and π^i at some later time $t_1 > t_0$.

Gauss constraint

The Yang-Mills equations (in temporal gauge) are

1) the **equations of motion** which follow from $\frac{\delta S[A_\mu]}{\delta A_i} = 0$ for $i \in \{1, 2, 3\}$

$$\partial_0 \pi^i = \partial_j F^{ji} + ig [A_j, F^{ji}]$$

$$\partial_0 A_i = \pi^i$$

2) and the **Gauss constraint** which follows from $\frac{\delta S[A_\mu]}{\delta A_0} = 0$

$$\partial_i \pi^i + ig [A_i, \pi^i] = 0$$

The Gauss constraint does not tell us about the “dynamics” of the fields (no time derivatives), but constrains the possible solutions for π^i and A_i .

Gauss constraint

If we choose initial values $\pi^i(t_0, \vec{x})$ and $A_i(t_0, \vec{x})$ at some initial time t_0 , which satisfy the Gauss constraint

$$\partial_i \pi^i(t_0, \vec{x}) + ig \left[A_i(t_0, \vec{x}), \pi^i(t_0, \vec{x}) \right] = 0,$$

the solutions of the equations of motion (EOM) $\pi^i(t, \vec{x})$ and $A_i(t, \vec{x})$ with $t > t_0$ will also satisfy the constraint.

More generally: if $\pi^i(t_0, \vec{x})$ and $A_i(t_0, \vec{x})$ satisfy

$$\partial_i \pi^i(t_0, \vec{x}) + ig \left[A_i(t_0, \vec{x}), \pi^i(t_0, \vec{x}) \right] = C(\vec{x}) \in \mathfrak{su}(N_c),$$

then the solutions of the EOM will conserve the quantity C , i.e.

$$\partial_i \pi^i(t, \vec{x}) + ig \left[A_i(t, \vec{x}), \pi^i(t, \vec{x}) \right] = C(\vec{x}),$$

for $t > t_0$. The EOM **conserve** the constraint.

Gauss constraint

Gauss constraint with non-zero right hand side:

$$\partial_i \pi^i(t, \vec{x}) + ig \left[A_i(t, \vec{x}), \pi^i(t, \vec{x}) \right] = C(\vec{x}),$$

Explicit proof: consider $C(t, \vec{x})$ as a function of time t . Then compute

$$\frac{dC}{dt} = \partial_i \partial_0 \pi^i(t, \vec{x}) + ig \left[\partial_0 A_i(t, \vec{x}), \pi^i(t, \vec{x}) \right] + ig \left[A_i(t, \vec{x}), \partial_0 \pi^i(t, \vec{x}) \right]$$

and insert EOM

$$\partial_0 \pi^i = \partial_j F^{ji} + ig \left[A_j, F^{ji} \right],$$

$$\partial_0 A_i = \pi^i,$$

to find $dC/dt = 0$. Also works without gauge fixing.

Gauss constraint

More general: the conservation of the Gauss constraint is a consequence of gauge symmetry.

The action $S[A_\mu]$ is invariant under gauge transformations

$$A'_\mu = \Omega \left(A_\mu + \frac{1}{ig} \partial_\mu \right) \Omega^\dagger$$

Consider a “small” gauge transformation

$$\Omega = \exp(ig\alpha) \simeq \mathbf{1} + ig\alpha + \mathcal{O}(\alpha^2)$$

We then have

$$\begin{aligned} A'_\mu &\simeq A_\mu + \partial_\mu \alpha + ig [A_\mu, \alpha] + \mathcal{O}(\alpha^2) \\ &\simeq A_\mu + D_\mu \alpha + \mathcal{O}(\alpha^2) \end{aligned}$$

Gauss constraint

Gauge symmetry: $S[A'_\mu] = S[A_\mu]$

Since $S[A_\mu + D_\mu\alpha] = S[A_\mu]$ (gauge invariance) we can expand $S[A'_\mu]$ up to linear order in α and set the coefficient to zero.

$$\delta S[A_\mu, D_\mu\alpha] = \int d^4x \frac{\delta S}{\delta A_\mu^a} (D_\mu\alpha)^a,$$

where

$$(D_\mu\alpha)^a = \partial_\mu\alpha^a - gf^{abc}A_\mu^b\alpha^c$$

Use integration by parts and anti-symmetry of f^{abc}

$$\delta S[A_\mu, D_\mu\alpha] = - \int d^4x \alpha^a \left((\delta^{ac}\partial_\mu - gf^{abc}A_\mu^b) \frac{\delta S}{\delta A_\mu^c} \right)$$

Gauss constraint

Since S is gauge invariant, this expression must be identically zero

$$\delta S[A_\mu, D_\mu \alpha] = - \int d^4x \alpha^a \left((\delta^{ac} \partial_\mu - g f^{abc} A_\mu^b) \frac{\delta S}{\delta A_\mu^c} \right) = 0,$$

which implies

$$(\delta^{ac} \partial_\mu - g f^{abc} A_\mu^b) \frac{\delta S}{\delta A_\mu^c} = 0$$

or simply

$$D_\mu \frac{\delta S}{\delta A_\mu} = 0, \quad \frac{\delta S}{\delta A_\mu} = \frac{\delta S}{\delta A_\mu^a} t^a.$$

Gauss constraint

In temporal gauge ($A_0 = 0$) this leads to

$$\partial_0 \frac{\delta S}{\delta A_0} = D_i \frac{\delta S}{\delta A_i} = 0$$

if the EOM are satisfied $\frac{\delta S}{\delta A_i} = 0$. The constraint is conserved.

Without gauge fixing we find $D_0 \frac{\delta S}{\delta A_0} = 0$. If the constraint is satisfied at some time t_0 , then it will also be satisfied at $t \neq t_0$.

Gauss constraint

Write $C(t, \vec{x}) = \frac{\delta S}{\delta A_0}$. The equation $D_0 C(t, \vec{x}) = 0$ is solved by

$$C(t_1, \vec{x}) = \Omega(t_1, t_0; \vec{x}) C(t_0, \vec{x}) \Omega^\dagger(t_1, t_0; \vec{x}),$$

with

$$\partial_t \Omega(t, t_0; \vec{x}) = -ig A_0(t, \vec{x}) \Omega(t, t_0; \vec{x}), \quad \Omega(t_0, t_0; \vec{x}) = \mathbf{1}.$$

This is solved by the path-ordered exponential

$$\Omega(t_1, t_0; \vec{x}) = \mathcal{P} \exp \left(-ig \int_{t_0}^{t_1} dt' A_0(t', \vec{x}) \right).$$

If $C(t_0, \vec{x}) = 0$ then also $C(t, \vec{x}) = 0$ for $t \neq t_0$.

Gauss constraint: summary

- ▶ The Gauss constraint follows from the variation of $S[A_\mu]$ with respect to A_0
- ▶ The equations of motion conserve the Gauss constraint
- ▶ The conservation of the Gauss constraint does not depend on the exact form of the EOM or the constraint, but is a consequence of gauge invariance

The more general theorem all this follows from is known as **Noether's second theorem**, which is valid for local (gauge), continuous symmetries of the action. **Noether's first theorem** applies to global continuous symmetries. See e.g. [\[arXiv:1601.03616\]](https://arxiv.org/abs/1601.03616) for a review on (gauge) symmetries and Noether's theorems.

Energy-momentum tensor

Energy-momentum tensor

Many quantities such as A_μ or $F_{\mu\nu}$ change under gauge transformations and can therefore not be physically observable. Physical observables must be gauge invariant.

One particular example: the energy-momentum tensor

$$T^{\mu\nu} = F^{a,\mu\rho} F_{\rho}^{a,\nu} - \frac{1}{4} g^{\mu\nu} F^{a,\rho\sigma} F_{\rho\sigma}^a$$

Invariance is easy to show: rewrite

$$T^{\mu\nu} = 2 \operatorname{tr} \left(F^{\mu\rho} F_{\rho}^{\nu} - \frac{1}{4} g^{\mu\nu} F^{\rho\sigma} F_{\rho\sigma} \right)$$

and use $F'_{\mu\nu} = \Omega F_{\mu\nu} \Omega^\dagger$.

Energy-momentum tensor

Energy-momentum tensor (or stress-energy tensor)

$$T^{\mu\nu} = F^{a,\mu\rho} F_{\rho}^{a,\nu} - \frac{1}{4} g^{\mu\nu} F^{a,\rho\sigma} F_{\rho\sigma}^a$$

$T_{\mu\nu}$ is a main object of interest in the earliest stages of heavy-ion collisions. Many experimental observations (properties of particles measured in detectors) depend on $T_{\mu\nu}$ shortly after the collision.

- ▶ T^{00} : energy density
- ▶ T^{i0} : energy flux in along x^i axis
- ▶ T^{ij} for $i = j$: pressure density components
- ▶ T^{ij} for $i \neq j$: shear stress

Energy-momentum tensor

Energy-momentum tensor (or stress-energy tensor)

$$T^{\mu\nu} = F^{a,\mu\rho} F_{\rho}^{a,\nu} - \frac{1}{4} g^{\mu\nu} F^{a,\rho\sigma} F_{\rho\sigma}^a$$

and its conservation law

$$\partial_{\mu} T^{\mu\nu} = 0$$

can be derived from the invariance of $S[A_{\mu}]$ under space-time translations

$$x'^{\mu} = x^{\mu} + w^{\mu}$$

for arbitrary, constant translation vectors w^{μ} .

This follows from Noether's first theorem, which applies to global (x independent) continuous symmetries.

Electromagnetism

Electromagnetism as a $U(1)$ gauge theory

Electromagnetism is an Abelian gauge theory with a $U(1)$ gauge symmetry

The Lie group $U(1)$

$U(1)$ consists of complex numbers $u \in \mathbb{C}$ with $|u| = 1$

$$u = \exp(i\theta) \in U(1), \quad \theta \in \mathbb{R}$$

$$uu' = \exp(i\theta) \exp(i\theta') = \exp(i(\theta + \theta')) \in U(1), \quad \theta, \theta' \in \mathbb{R}$$

$$u^{-1} = \exp(-i\theta) = u^* \in U(1)$$

The Lie algebra of $U(1)$ is simply \mathbb{R}

Electromagnetism as a $U(1)$ gauge theory

Degrees of freedom: Abelian gauge fields $A_\mu : \mathbf{M} \rightarrow \mathbb{R}$

(Abelian) Field strength tensor

$$F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$$

Note: $U(1)$ is Abelian: no commutator term

Just a “single color component”: no need for an index

Action

$$S[A_\mu] = \int d^4x \left(-\frac{1}{4} F_{\mu\nu} F^{\mu\nu} \right)$$

Note: no trace

Action is invariant under $U(1)$ gauge symmetry

Electromagnetism as a $U(1)$ gauge theory

Gauge symmetry

Gauge transformations in (non-Abelian) Yang-Mills theory

$$A'_\mu(x) = \Omega(x) \left(A_\mu(x) + \frac{1}{ig} \partial_\mu \right) \Omega^\dagger(x)$$

with $\Omega : \mathbf{M} \rightarrow \text{SU}(N_c)$, $g > 0$ Yang-Mills coupling constant

Gauge transformations in $U(1)$ gauge theory

$$A'_\mu(x) = \Omega(x) \left(A_\mu(x) + \frac{1}{ie} \partial_\mu \right) \Omega^*(x)$$

with $\Omega(x) : \mathbf{M} \rightarrow U(1)$, $e > 0$ elementary electric charge

Electromagnetism as a $U(1)$ gauge theory

Gauge symmetry

Gauge transformations in $U(1)$ gauge theory

$$A'_\mu(x) = \Omega(x) \left(A_\mu(x) + \frac{1}{ie} \right) \Omega^*(x)$$

with $\Omega : \mathbf{M} \rightarrow U(1)$, $e > 0$ elementary electric charge

Write $\Omega(x) = \exp(ie\alpha(x))$ with $\alpha : \mathbf{M} \rightarrow \mathbb{R}$.

$$\begin{aligned} A'_\mu(x) &= \Omega(x) \left(A_\mu(x) + \frac{1}{ie} \partial_\mu \right) \Omega^*(x) \\ &= \Omega(x) A_\mu(x) \Omega^*(x) + \frac{1}{ie} \Omega(x) \partial_\mu \Omega^*(x) \\ &= A_\mu(x) - \partial_\mu \alpha(x) \end{aligned}$$

Adding a gradient term to A_μ leaves $S[A_\mu]$ invariant

Electromagnetism as a $U(1)$ gauge theory

Gauge symmetry

Field strength tensor

$$F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$$

Gauge transformations:

$$F'_{\mu\nu} = \Omega F_{\mu\nu} \Omega^* = F_{\mu\nu}$$

In $U(1)$ gauge theory, the field strength tensor is gauge invariant and therefore a physical observable

\Rightarrow Electric and magnetic fields are observables

Electromagnetism as a $U(1)$ gauge theory

Maxwell's equations

Vary $S[A_\mu]$ to obtain the classical equations of motion

$$\partial_\mu F^{\mu\nu} = 0$$

Use $F_{0i} = E_i$ and $F_{ij} = \varepsilon_{ijk} B_k$ to find

$$\nabla \cdot \vec{E} = 0, \quad \frac{\partial \vec{E}}{\partial t} = \nabla \times \vec{B}$$

The other two Maxwell equations

$$\nabla \cdot \vec{B} = 0, \quad \frac{\partial \vec{B}}{\partial t} = -\nabla \times \vec{E}$$

follow from the definition of the magnetic field $B_i = -\frac{1}{2}\varepsilon_{ijk} F_{jk}$ and the other two equations.