

On the Complexity of Infinite-Dimensional Quadrature Problems

Thomas Müller-Gronbach, Uni Passau

Infinite-Dimensional Quadrature Problems

Given

- a Borel probability measure μ on a separable Banach space $(\mathfrak{X}, \|\cdot\|)$,
- a class F of functionals $f : \mathfrak{X} \rightarrow \mathbb{R}$.

Compute

$$\int_{\mathfrak{X}} f d\mu \quad \text{for } f \in F.$$

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Examples

- μ Wiener measure on $\mathfrak{X} = C([0, 1])$ (\leftrightarrow path integrals).

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 - SDE on the path space $\mathfrak{X} = C([0, 1], \mathbb{R}^k)$ (\leftrightarrow comp. finance),

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 - SDE on the path space $\mathfrak{X} = C([0, 1], \mathbb{R}^k)$ (\leftrightarrow comp. finance),
 - SPDE on the path space $\mathfrak{X} = C([0, 1], L_2(D))$ (\leftrightarrow fluid dyn.).

Outline

- Complexity of Numerical Problems
- Setup for Infinite-Dim. Quadrature: Algorithms, Error, Cost
- Results for $F = \text{Lip}(1)$
 - SDEs
 - The general case
 - Gaussian measures

Complexity of Numerical Problems

- (I) **Computational problem:** quadrature, PDE, optimization, ...
- (II) **Computational means:** class \mathcal{A} of algorithms.
- (III) **Quality criterion:** error and cost of an algorithm.
- (IV) **Minimal error and complexity:**

$$e_N = \inf\{\text{error}(A) : A \in \mathcal{A} \text{ such that } \text{cost}(A) \leq N\},$$
$$\text{comp}(\varepsilon) = \inf\{\text{cost}(A) : A \in \mathcal{A} \text{ such that } \text{error}(A) \leq \varepsilon\}.$$

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Leads to

- benchmarks for existing algorithms,
- definition of optimal algorithms,
- construction of new algorithms (sometimes).

Typical result

$$e_N \asymp N^{-\alpha},$$

consists of

- **upper bound:** existence (construction) of algorithms $A_N \in \mathcal{A}$ with

$$\text{cost}(A_N) \leq N \quad \wedge \quad \text{error}(A_N) = O(N^{-\alpha}),$$

- **lower bound:** $\exists c > 0 \quad \forall$ algorithm $A \in \mathcal{A}$:

$$\text{cost}(A) \leq N \quad \Rightarrow \quad \text{error}(A) \geq c \cdot N^{-\alpha}.$$

See

*Traub, Wasilkowski, Woźniakowski (1988), Novak (1988),
Werschulz (1991), Plaskota (1996), Ritter (2000), ...*

Algorithms, Error, and Cost

(I) **Problem:** Compute $S(f) = \int_{\mathfrak{X}} f d\mu$ for $f \in F$.

(II) **Randomized algorithm** for approximation of $S : F \rightarrow \mathbb{R}$

$$\widehat{S} : F \times \Omega \rightarrow \mathbb{R}$$

with any probability space $(\Omega, \mathcal{A}, \mathbb{P})$, where

$$\widehat{S}(f, \omega) = \varphi(\omega, f(X_1(\omega)), \dots, f(X_{\nu(\omega)}(\omega)))$$

and

$$X_i(\omega) \in \mathfrak{X} \quad \text{(full space sampling).}$$

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(III) **Error and cost**

$$\text{error}(\widehat{S}) = \sup_{f \in F} \left(\mathbb{E} |\widehat{S}(f) - S(f)|^2 \right)^{1/2}, \quad \text{cost}(\widehat{S}) = \mathbb{E}(\nu).$$

Remark

1. More generally, we cover adaptive algorithms, too.
2. In the case $\dim(\mathcal{X}) < \infty$
numerous results (algorithms, complexity) for explicitly or implicitly given distributions μ .
3. In the case $\dim(\mathcal{X}) = \infty$
sampling of f at any point $x \in \mathcal{X}$ at unit cost is unrealistic in general.

Reasonable restrictions

a) For any finite-dimensional subspace $\mathfrak{X}_0 \subset \mathfrak{X}$

$$X_1(\omega), \dots, X_{\nu(\omega)}(\omega) \in \mathfrak{X}_0 \quad \text{(fixed subspace sampling)}$$

$$\text{cost}(\hat{S}) = \mathbb{E}(\nu) \cdot \dim \mathfrak{X}_0.$$

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Example: Consider an SDE and the Monte-Carlo Euler scheme

$$\widehat{S}(f) = 1/n \sum_{i=1}^n f(X_{i,k})$$

with step-size $1/k$ and piecewise linear interpolation. Then

$$\text{cost}(\widehat{S}) \asymp n \cdot k = \# \text{replications} \cdot \# \text{Euler steps}.$$

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b) For any scale of finite-dimensional subspaces $\mathfrak{X}_1 \subset \mathfrak{X}_2 \subset \dots \subset \mathfrak{X}$

$$X_1(\omega), \dots, X_{\nu(\omega)}(\omega) \in \bigcup_{m=1}^{\infty} \mathfrak{X}_m \quad \text{(variable subspace sampling)}$$

$$\text{cost}(\widehat{S}) = \mathbb{E} \left(\sum_{i=1}^{\nu} \inf \{ \dim \mathfrak{X}_m : X_i \in \mathfrak{X}_m \} \right).$$

(IV) Minimal Errors (in all three sampling regimes)

$$e_N = \inf \{ \text{error}(\hat{S}) : \text{cost}(\hat{S}) \leq N \}.$$

Notation

e_N^{full} : full space sampling

e_N^{fix} : fixed subspace sampling

e_N^{var} : variable subspace sampling

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Questions

- Order of convergence of $e_N^{\text{full}} \leq e_N^{\text{var}} \leq e_N^{\text{fix}}$?
- Construction of algorithms \hat{S}_N such that

$$\text{cost}(\hat{S}_N) \leq N \quad \text{and} \quad \text{error}(\hat{S}_N) \asymp e_N?$$

Results

In the sequel we consider the class

$$F = \text{Lip}(1)$$

of functionals $f : \mathfrak{X} \rightarrow \mathbb{R}$ with

$$|f(x) - f(y)| \leq \|x - y\|, \quad x, y \in \mathfrak{X}.$$

Concerning μ we consider

- the SDE case,
- the general case,
- the case of Gaussian measures.

The SDE Case

Consider

$$\begin{aligned}dX(t) &= a(X(t)) dt + b(X(t)) dW(t), \quad t \in [0, 1], \\ X(0) &= u_0 \in \mathbb{R},\end{aligned}$$

where

- a Lipschitz,
- $b \in C^2(\mathbb{R})$, b' , b'' bounded,
- $b(u_0) \neq 0$.

Let μ denote the distribution of X on $\mathfrak{X} = C([0, 1])$.

Theorem 1 (*Creutzig, Dereich, M-G, Ritter 09*)

$$N^{-1/4} \cdot (\ln N)^{-3/4} \preceq e_N^{\text{fix}} \preceq N^{-1/4} \quad \text{(fixed subspace)}$$

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Remark Upper bounds (up to powers of $\ln N$)

- for fixed subspace sampling: Monte-Carlo Euler,
- for variable subspace sampling: multilevel Monte-Carlo Euler.

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The basic idea

$$\mathbb{E}(f(X_L)) = \sum_{\ell=2}^L \mathbb{E}(f(X_\ell) - f(X_{\ell-1})) + \mathbb{E}(f(X_1)).$$

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Math Finance: *Giles* (2008, ...), *Giles, Higham, Mao* (2009),
Avikainen (2009), *Giles, Watherhouse* (2009).
Levy-driven, fractional driven SDEs: *Dereich* (2009),
Dereich, Heidenreich (2009), *Kloeden, Neuenkirch, Pavani* (2009),
Initiated by: *Heinrich* (1998), *Heinrich, Sindambiwe* (1999)
for integral equations, parametric integration.

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- for fixed subspace sampling: Monte-Carlo Euler,
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Note Strong optimality property of the multilevel algorithm.

The General Case

Basis for analysis and results: approximation of distributions.

Wasserstein metric of order $r \geq 1$

$$\Delta^{(r)}(\mu, \tilde{\mu}) = \inf_{\rho} \left(\int_{\mathfrak{X} \times \mathfrak{X}} \|x - y\|^r d\rho(x, y) \right)^{1/r}$$

with inf over all Borel prob. measures ρ on $\mathfrak{X} \times \mathfrak{X}$ with marginals $\mu, \tilde{\mu}$.

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Connection to quadrature problem on $F = \text{Lip}(1)$:

Kantorovich-Rubinstein Theorem

$$\Delta^{(1)}(\mu, \tilde{\mu}) = \sup_{f \in F} \left| \int_{\mathfrak{X}} f d\mu - \int_{\mathfrak{X}} f d\tilde{\mu} \right|.$$

N -th quantization number of order r

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$$N^{1/2} \cdot \sup_{n \geq 4N} (q_{n-1}^{(1)} - q_n^{(1)}) \preceq e_N^{\text{full}} \preceq N^{-1/2} \cdot q_N^{(2)}$$

$$\max(e_N^{\text{full}}, d_{2N}^{(1)}) \preceq e_N^{\text{var}}$$

$$\inf_{k \cdot n \leq N} \max(e_n^{\text{full}}, d_k^{(1)}) \preceq e_N^{\text{fix}} \preceq \inf_{k \cdot n \leq N} (n^{-1/2} + d_k^{(2)})$$

If $d_N^{(2)}$ is regular varying: $e_N^{\text{var}} \preceq \max(N^{-1/2}, d_N^{(2)}) \cdot \ln N.$

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For SDEs $q_N^{(r)} \asymp (\ln N)^{-1/2}, d_N^{(r)} \asymp N^{-1/2}.$

Quantization numbers

Finite-dimensional spaces: studied since around 1950

Graf, Luschny (2000)

Infinite-dimensional spaces: studied since around 2000

*Aurzada, Creutzig, Dereich, Fehring, Luschny, M-G, Matoussi,
Pagès, Printems, Ritter, Scheutzow,...*

Applications to computational finance:

Pagès, Pham, Printems (2004), Pagès, Printems (2005)

Quantization numbers

Average Kolmogorov widths

Gaussian measures:

Mathé (1990), Maiorov (1992,...), ..., Creutzig (2002)

Diffusion processes:

Creutzig, Dereich, M-G, Ritter (2009)

Quantization numbers

Average Kolmogorov widths

Optimal algorithms for quadrature problems

Finite dimensional spaces:

Nikolskij (1950), Kiefer (1957), Bakhvalov (1959), ...

Infinite dimensional spaces:

Wasilkowski, Woźniakowski (1996),

Creutzig, Dereich, M-G, Ritter (2009),

Hickernell, Niu (2009)

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The Gaussian Case

Small ball probabilities for centered Gaussian measure μ on \mathfrak{X}

$$\varphi(\varepsilon) = -\ln \mu(\{x \in \mathfrak{X} : \|x\| \leq \varepsilon\}).$$

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$$\exists \alpha > 0, \beta \in \mathbb{R} : \quad \varphi(\varepsilon) \asymp \varepsilon^{-\alpha} \cdot (\ln \varepsilon^{-1})^\beta \quad \text{as } \varepsilon \rightarrow 0.$$

See ... *Li, Shao (2001), Belinski, Linde (2002), Fill, Torcaso (2004), ...*

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Example: Fractional Brownian motion with Hurst index $H \in]0, 1[$ on $\mathfrak{X} = C[0, 1]$. Here

$$\alpha = 1/H, \quad \beta = 0.$$

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Proposition *Creutzig (2002), Dereich (2003)*

$$q_N^{(r)} \asymp (\ln N)^{-1/\alpha} \cdot (\ln \ln N)^{\beta/\alpha}, \quad d_N^{(r)} \asymp N^{-1/\alpha} \cdot (\ln N)^{\beta/\alpha}.$$

Assumption $-\ln \mu(\{x \in \mathfrak{X} : \|x\| \leq \varepsilon\}) \asymp \varepsilon^{-\alpha} \cdot (\ln \varepsilon^{-1})^\beta$

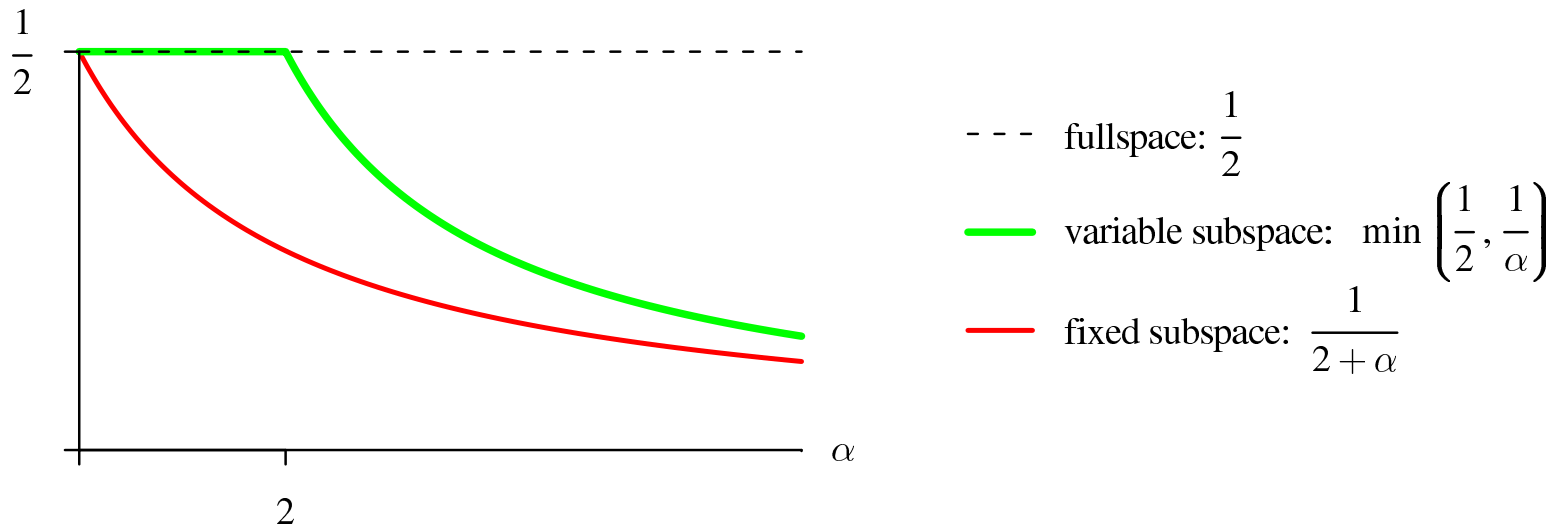
Theorem 3 (Creutzig, Dereich, M-G, Ritter 09) Up to powers of $\ln N$

$$0 < \limsup_{N \rightarrow \infty} N^{1/2} \cdot e_N^{\text{full}} < \infty$$

$$0 < \limsup_{N \rightarrow \infty} N^{1/2} \cdot e_N^{\text{var}} < \infty \quad \text{for } \alpha < 2$$

$$e_N^{\text{var}} \asymp N^{-1/\alpha} \quad \text{for } \alpha \geq 2$$

$$0 < \limsup_{N \rightarrow \infty} N^{1/(2+\alpha)} \cdot e_N^{\text{fix}} < \infty$$



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- Hereby: upper and lower bounds for minimal errors on $F = \text{Lip}(1)$.
- In particular, for SDEs,
var. subspace: $N^{-1/2}$, **fixed subspace:** $N^{-1/4}$,
and for Gaussian measures with ‘smoothness’ $1/\alpha \in]0, \infty[$
var. subspace: $N^{-1/\max(2,\alpha)}$, **fixed subspace:** $N^{-1/(2+\alpha)}$
(up to powers of $\ln N$).

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var. subspace: $N^{-1/\max(2,\alpha)}$, **fixed subspace:** $N^{-1/(2+\alpha)}$
(up to powers of $\ln N$).
- Optimality of multilevel Monte-Carlo methods