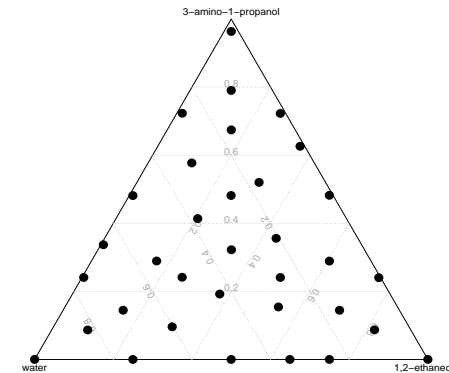


# Single-Index Signal Regression

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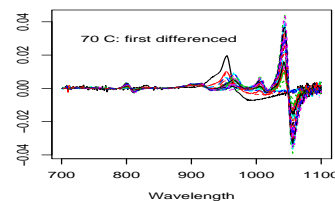
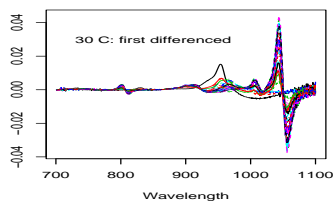
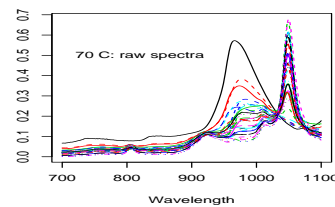
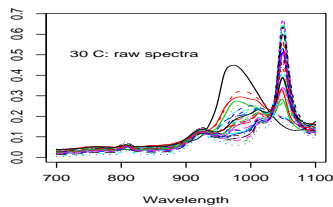
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## Signal regressors for mixture experiment

- Two (2) temperatures presented ( $30^\circ$ ,  $70^\circ$ )
- Raw and first differenced signals



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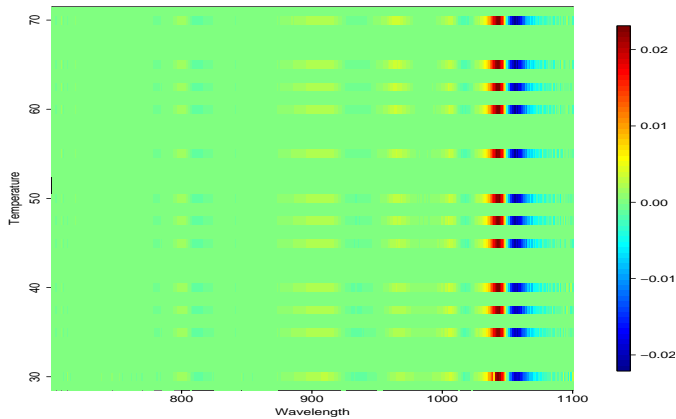
## “Rich” signal regressor information

- Digitized optical UV-spectra,  $p = 400$
- Ordered structure: 701 to 1100, by 1 nm
- Further: separate spectra at  $\check{p} = 12$  temperatures
- 30, 35, 37.5, 40, 45, 47.5, 50, 55, 60, 62.5, 65,  $70^\circ$  C
- In total:  $p \times \check{p} = 4800$ , for each observation
- Ironic note: we have too much information for OLS
- Many proposals for “regularization”

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## Exploit “spatial” structure in regressors

- Two-dimensional (first differenced) signal regressor image
- Regressor image for center mixture  $(\frac{1}{3}, \frac{1}{3}, \frac{1}{3})$
- Each mixture has unique regressor image



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## Simultaneous goals

- Parse out two separate modeling components
  1. A single smooth 2D (linear) *coefficient* surface
  2. An unknown *nonlinear* link function
- Explicit modeling of each component
- Nonlinearity could add insight to measurement process
- Combination: systematic, tractable, competitive
- Aim: reliable prediction + interpretability

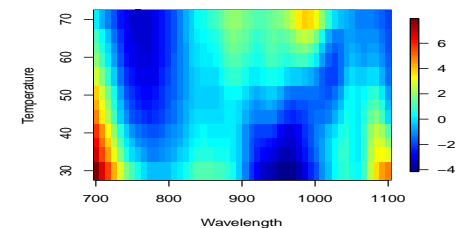
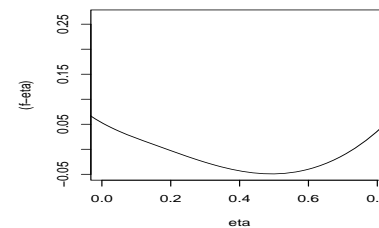
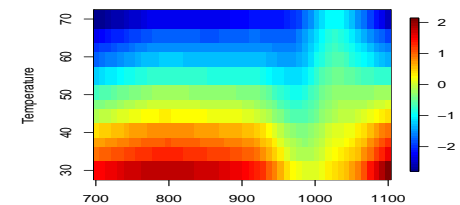
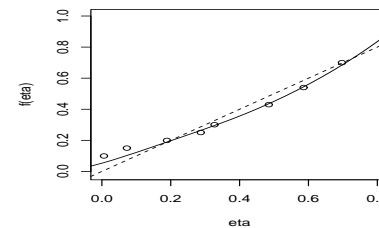
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## The data structure

- Each obs, data pair:  $(y_i, X_i)$ ,  $i = 1, \dots, m$
- Responses  $y$ : independent, common  $\sigma^2$
- Regressors  $X_i$  (thousands of digitizations)
- $(4800) p \times \check{p}$  common 2-D array
- Regressor support:  $v \times \check{v}$  (UV-channel, temperature)

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## “Deliverable” for Isopropanol



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## Model formulation

### Standard (penalized) signal regression

$$\mu_i = \sum_{j=1}^p \sum_{k=1}^{\check{p}} x_{ijk} \alpha_{jk}$$

Estimate  $\alpha$  as smooth surface

### Single-index signal regression

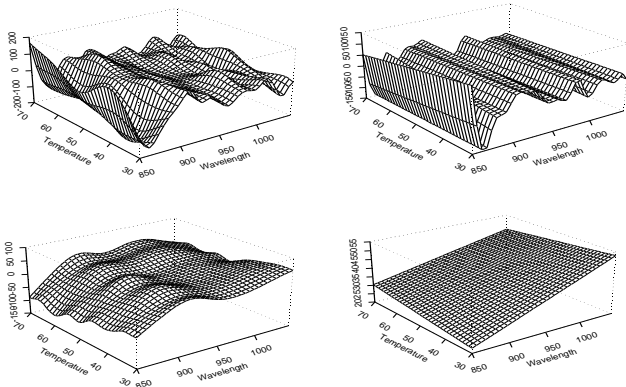
$$\mu_i = f\left(\sum_{j=1}^p \sum_{k=1}^{\check{p}} x_{ijk} \alpha_{jk}\right)$$

Unknown (univariate)  $f$ , with own smoothness penalty

Related to Projection Pursuit: Friedman and Stuetzle (1981)

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## Examples: (tensor product) coefficient surfaces



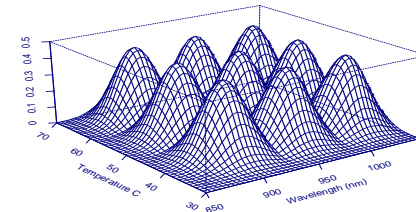
## Signal regression portion

- “Unfold” coefficient surface with tensor product B-splines

$$\text{vec}(\alpha) = \mathbf{T}\gamma$$

$$\text{vec}(\mu) = X\alpha = \underbrace{X}_{\mathbf{M}} \mathbf{T}\gamma$$

- (Rich/ Sparse)  $\mathbf{T}$ : constant  $\gamma$   $\dim(\mathbf{M}) : m \times (n\check{n})$



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## Penalizing the coefficient surface

- Minimize:

$$\begin{aligned} Q_P(\gamma) &= \text{Residual SS} + \text{Row Penalty} + \text{Column Penalty} \\ &= \|y - \mathbf{M}\gamma\|^2 + \lambda \|P\gamma\|^2 + \check{\lambda} \|\check{P}\gamma\|^2, \end{aligned}$$

- Penalties directly on  $\gamma$  (tensor product coefficients)
- Two positive tuning parameters:  $\lambda, \check{\lambda}$
- Compact representation of penalties:

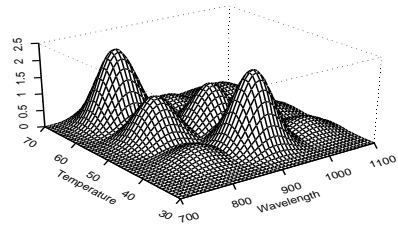
$$P = (D'_d D_d) \otimes I_{\check{n}} \quad \text{and} \quad \check{P} = I_n \otimes (D'_d D_d)$$

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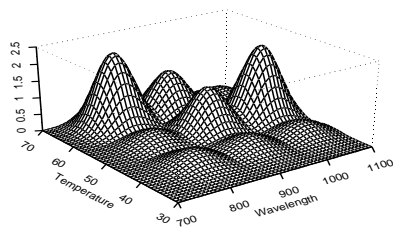
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## Penalties in "action" (coefficient surface)

Strong row penalty



Strong column penalty



### Explicit solution:

$$\hat{\gamma} = (\mathbf{M}'\mathbf{M} + \lambda P'P + \check{\lambda} \check{P}'\check{P})^{-1} \mathbf{M}'y$$

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## Estimation, for fixed $f$

### Approximate:

$$f(\mathbf{M}\gamma) \approx f(\mathbf{M}\gamma_0) + \dot{f}(\mathbf{M}\gamma_0)\mathbf{M}(\gamma - \gamma_0)$$

### Objective:

$$\begin{aligned} Q_P^* &\approx \|y - f(\mathbf{M}\gamma_0) - \dot{f}(\mathbf{M}\gamma_0)\mathbf{M}(\gamma - \gamma_0)\|^2 + \lambda \|P\gamma\|^2 + \check{\lambda} \|\check{P}\gamma\|^2 \\ &= \|y^* - \mathbf{M}^*\gamma\|^2 + \lambda \|P\gamma\|^2 + \check{\lambda} \|\check{P}\gamma\|^2 \end{aligned}$$

- Boils down to:  $\text{PSR}(\mathbf{M}^*, y^*, (\lambda, \check{\lambda}), (D_d, D_{\check{d}}), (n, \check{n}))$

- Modified response and regressors:

$$y^* = y - f(\mathbf{M}\gamma_0) + \dot{f}(\mathbf{M}\gamma_0)\mathbf{M}\gamma_0 \quad \text{and} \quad \mathbf{M}^* = \text{diag}\{\dot{f}(\mathbf{M}\gamma_0)\}\mathbf{M}$$

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## Bringing in $f$

### Modified objective:

$$Q_P^* = \|y - \underbrace{f(\mathbf{M}\gamma)}_{\eta}\|^2 + \lambda \|P\gamma\|^2 + \check{\lambda} \|\check{P}\gamma\|^2 + \lambda_f \|D_d \alpha\|^2$$

- $f$  one-dimensional (P-spline) smoothing  $(\eta, y)$
- Rich (univariate) B-spline basis
- $f$  has own  $\lambda_f$
- Bonus: First derivative  $\dot{f}$  easy to compute

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## Basics of fitting algorithm

- Initialize with  $\text{PSR}(M, y)$ : get  $\hat{\gamma}$
- Given  $\hat{\gamma}$ : get  $\hat{f}$  with  $S(\hat{\eta}, y)$
- Given  $\hat{f}$ : get derivative and modified  $y^*$ ,  $\mathbf{M}^*$
- Update  $\hat{\gamma}$ :  $\text{PSR}(\mathbf{M}^*, y^*)$
- Regularize norm of  $\hat{\gamma}$
- Cycle until convergence

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# Single-index signal regression algorithm

## 1. Initializations:

- Choose the tuning parameter values  $(\lambda, \check{\lambda}, \lambda_f)$  for Steps 1 and 2
- Choose number of knots  $(n, \check{n}, n_f)$
- Choose penalty order  $(d, \check{d}, d_f)$
- Set all tuning parameters to  $\lambda_0$  for the initial Step 1 (default  $10^6$ )
- Create  $\mathbf{M} = \mathbf{X}\mathbf{T}$
- Calculate  $\hat{\gamma} = \text{MPSR}(\mathbf{M}, y, (\lambda_0, \lambda_0), (d, \check{d}), (n, \check{n}))$

## 2. Cycle until convergence of $\hat{\gamma}$ 's

- Estimate  $\hat{f}$  and the estimate of the derivative  $\dot{f}$  from  $S(\mathbf{M}\hat{\gamma}, y, \lambda_f, d_f, n_f)$
- Obtain  $y^*$  and  $\mathbf{M}^*$
- Update  $\hat{\gamma} = \text{MPSR}(\mathbf{M}^*, y^*, (\lambda, \check{\lambda}), (d, \check{d}), (n, \check{n}))$
- Constrain  $\hat{\gamma}/\|\hat{\gamma}\|$

## 3. Prediction: $\hat{y}^{new} = \hat{f}(x^{new}\mathbf{T}\hat{\gamma})$

# (Optimal) tuning parameters

- Three (3) tuning parameters  $(\lambda, \check{\lambda}, \lambda_f)$ : nm, temp,  $f$

- Data splitting: training, validation, test sets

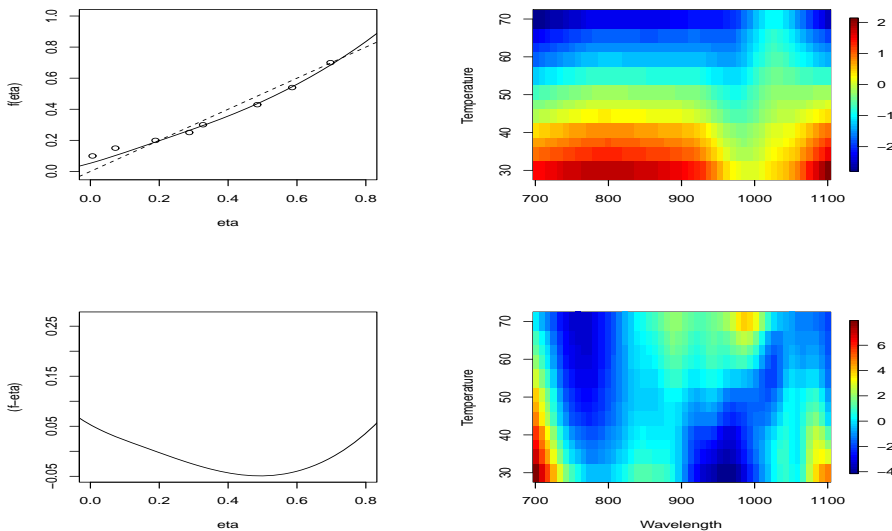
- Choose  $\lambda$ s to minimize:

$$\text{RMSEV} = \sqrt{\frac{1}{m^{valid}} \sum_{i=1}^{m^{valid}} (y_i - \hat{y}_{vi})^2}$$

- $\hat{y}_v$ : validation prediction, using training parameter estimates

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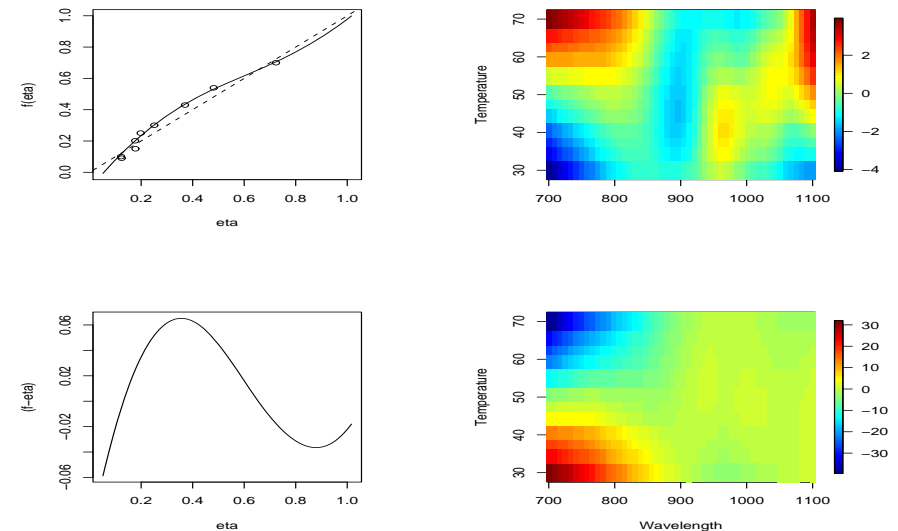
## Isopropanol (optimal model)



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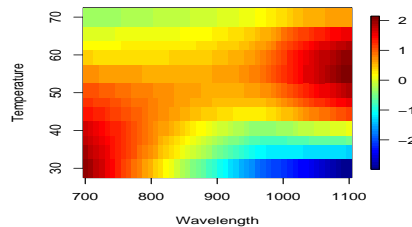
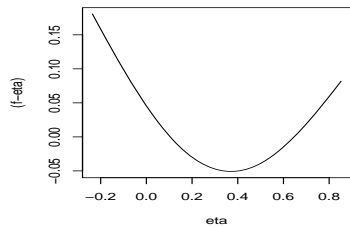
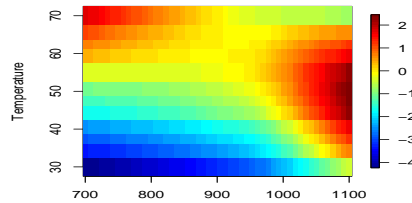
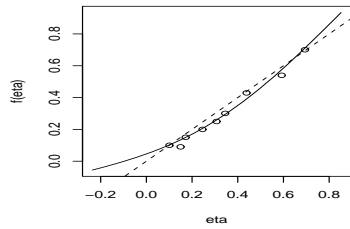
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## Water (optimal model)



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## Ethanol (optimal model)



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## Idea of prediction performance: RMSEP

Response	MSISR	MPSR	PLS
Water	0.0214	0.0365	0.0465
1,2-ethanediol	0.0241	0.0338	0.0382
3-amino-1-propanol	0.0306	0.0251	0.0359

- Using optimal models
- $\text{RMSEP} \times 100$ : units of percent mixture
- MSISR finds reductions of 30% to 55%

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## (External) prediction performance

- Given “optimal” model, evaluate

$$\text{RMSEP} = \sqrt{\frac{1}{m^{\text{test}}} \sum_{i=1}^{m^{\text{test}}} (y_i - \hat{y}_i)^2}$$

- $\hat{y}$ : test prediction, using combined (train, valid) estimates
- RMSEP is truly external

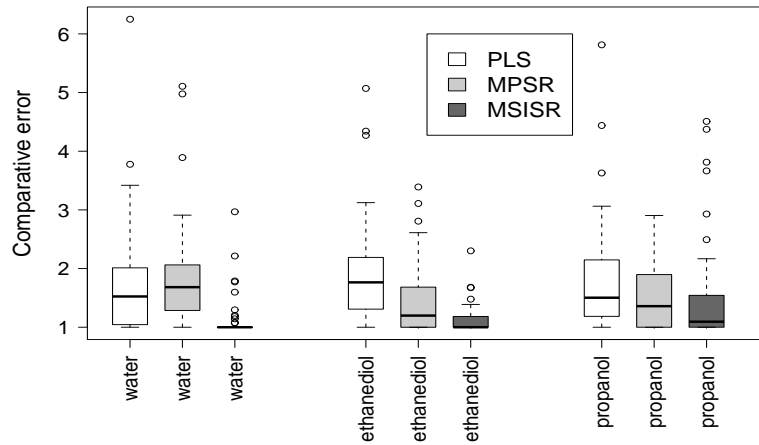
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## Details: data splitting

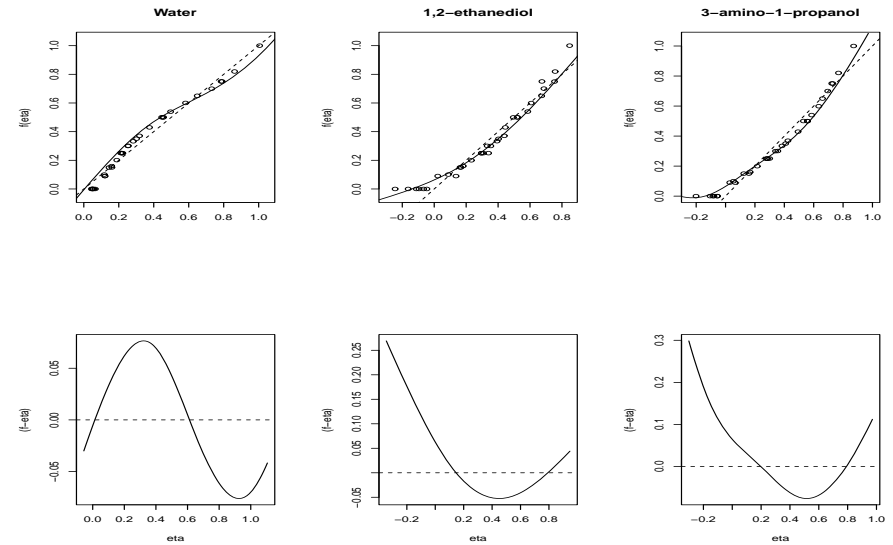
- $m = 34$  combinations (16 + 9 + 9)
- $16 = m^{\text{train}}$  (3 pure + 12 edge + 1 center)
- $9 = m^{\text{valid}} = m^{\text{test}}$  (each) interior
- Rank 18 interior: use odd (even) for valid (test)
- Fair and reasonable range of mixture levels
- No extrapolation in external prediction

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## External prediction: 50 random splits



## Closer view of $f$ : all mixtures, optimal $\lambda$ s

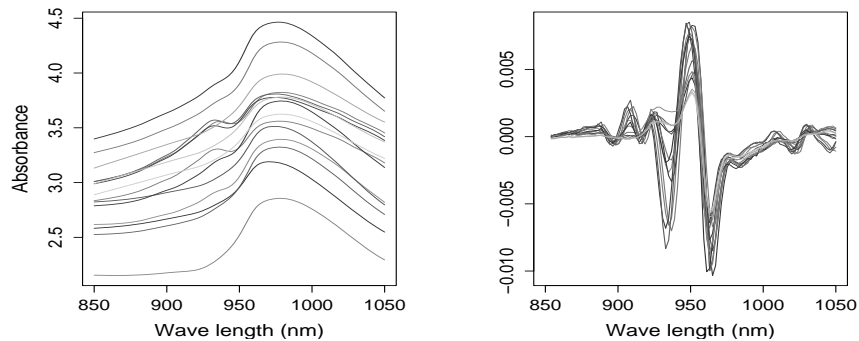


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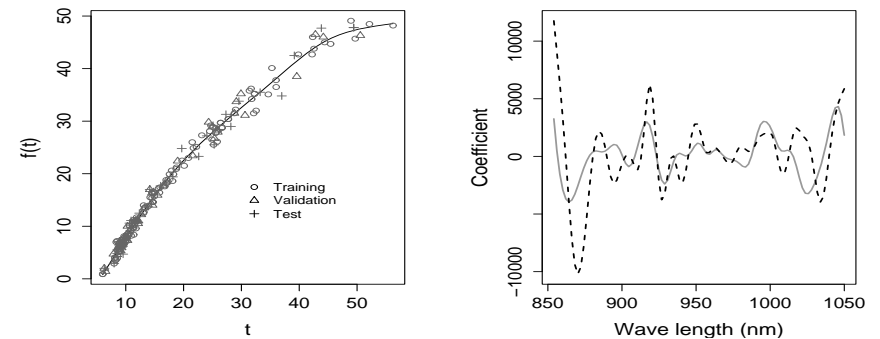
## SISR with 1D signals/spectra

- Main differences: 2D  $T$  is now 1D  $B$ ; thus no  $\tilde{\lambda}$
- (Example) Tecator data:  $m = 215$ : split 129/43/43
- Response: % fat;  $X$  contains NIR spectra (100 channel)



## Summary results for Tecator experiment

Method	$\lambda$	$d$	$n$	Valid Error	Test Error
PLS	—	—	—	2.83	2.86
PCR	—	—	—	2.82	2.92
PSR	$2.64 \times 10^{-8}$	3	100	2.74	1.85
SISR	$(3.36 \times 10^{-6}, 0.616)$	(3, 2)	(100, 20)	1.73	1.39



Eilers, Li, and Marx (2009), *Chemometrics and Intelligent Lab Sys*

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## SISR with binary response (GLM)

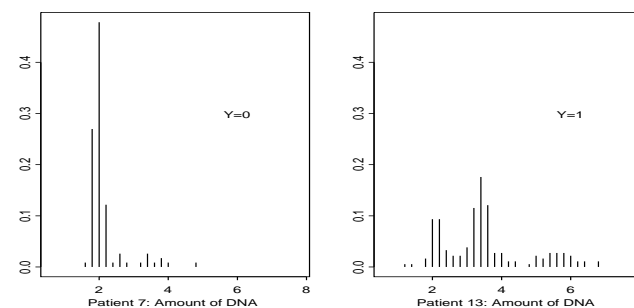
- Now use *iterative* weights:  $W = \text{diag}\{\pi(1 - \pi)\}$
- Adjusted “dependent variable”:  $\tilde{y} = W^{-1}(y - \pi) + \eta$
- Cascade functions:  $h(f(\eta))$
- $h$  inverse link
- $f$  modifier to  $h$

$$\log\left(\frac{\pi}{1 - \pi}\right) = f(\overset{\eta}{\mathbf{M}\alpha})$$

$$0 \equiv \frac{\partial l}{\partial \mu} \frac{\partial \mu}{\partial f} \frac{\partial f}{\partial \eta} \frac{\partial \eta}{\partial \alpha}$$

## Ovarian cancer: binary (GLM) example

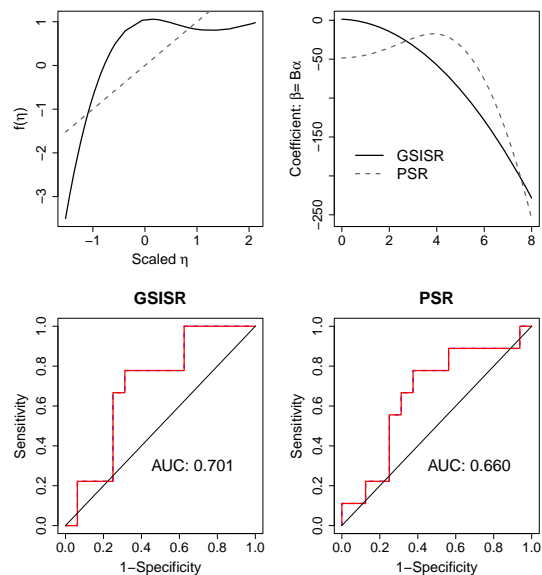
- $m = 70$  patients (28 “zeros” + 42 “ones”)
- Train 65 + Test 25
- Histogram signal (37 DNA bins)



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## Summary results for DNA experiment



## Some benefits of combined approach

1. An explicit (smooth)  $f$  can be estimated
2. Heavy penalization: polynomial  $f$
3. Entire signal used as regressors
4. Non-additive coefficient surface allowed
5. Important regions can be identified
6. Allows  $p \gg m$
7. Manageable system of equations
8. No “black box”/ No preprocessing
9. Can transplant to generalized linear model

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